

Amendments to the Claims:

This listing of claims will replace all prior versions and listings of claims in the application.

Listing of Claims:

1. (Currently amended) A motor driving method for a steering apparatus, comprising the steps of:
 - providing a steering system including a rack shaft and two motors disposed in spaced relation to one another for applying an auxiliary steering force to different positions on the rack shaft of the steering system;
 - in operating the two motors, operating one of the two motors first; and
 - after operating the first motor, operating the other motor,
 - wherein when only one of the two motors is being operated, motor failure detection for said only one motor is carried out.
2. (Previously presented) A motor driving method for a steering apparatus, comprising the steps of:
 - providing two motors for applying an auxiliary steering force to a steering system;
 - in operating the two motors, operating one of the two motors first; and
 - after operating the first motor, operating the other motor,
 - wherein in the step of operating one of the motors first, the two motors are used alternately.
3. (Original) A motor driving method according to claim 1, wherein in the step of operating one of the motors first, the same motor is always used.
4. (Previously presented) A motor driving method for a steering apparatus, comprising the steps of:
 - providing two motors for applying an auxiliary steering force to a steering system;
 - in operating the two motors, operating one of the two motors first; and
 - after operating the first motor, operating the other motor,

wherein in the step of operating one of the motors first, the same motor is always used, and

wherein when the steering direction is one direction a first of the motors is operated first and then the second motor is operated, and when the steering direction is the other direction the second motor is operated first and then the first motor is operated.

5. (Original) A motor driving method according to claim 1, wherein the output capacities of the two motors are different.

6. (Cancelled)

7-13. (Cancelled)

14. (New) A motor driving method according claim 2, wherein the output capacities of the two motors are different.

15. (New) A motor driving method according to 4, wherein the output capacities of the two motors are different.

16. (New) A motor driving method according to claim 2, wherein when only one of the two motors is being operated, motor failure detection for said only one motor is carried out.

17. (New) A motor driving method according to 4, wherein when only one of the two motors is being operated, motor failure detection for said only one motor is carried out.